

PROBLEM SET 1
Due Wednesday April 8

Problems marked with an asterisk will be graded.

1. Consider the operation O , represented by the 3×3 matrix O_{ij} which takes r into r' ;

$$r'_i = \sum_{j=1}^3 O_{ij} r_j.$$

Show that if we require that the length of r' to be the same as the length of r , then $O^T O = I$, or

$$\sum_i O_{ji}^T O_{ik} = \delta_{jk}$$

where O^T is the transpose of O . One also easily shows that $OO^T = I$. Transformations which satisfy the requirements $O^T O = OO^T = I$ are called orthogonal transformations. All that we are requiring is that the transformation preserve the length of r .

2. * We defined a three-dimensional vector as any object with three components which transformed like the coordinates; i.e.

$$A'_i = \sum_{j=1}^3 O_{ij} A_j,$$

where the operation O represents any translation or “proper” rotation. What we mean by “proper” is that it takes a right-handed coordinate system into a right-handed coordinate system. An “improper” rotation takes a right-handed system into a left-handed one. A reflection in a mirror does that, as does an inversion $\mathbf{r}' = O_{inv} \mathbf{r} = -\mathbf{r}$.

Let \mathbf{A} and \mathbf{B} be vectors. Under an inversion, $\mathbf{A} \rightarrow -\mathbf{A}$ and similarly for \mathbf{B} . Show that under an inversion, the dot product does not change. Show that the cross product, $\mathbf{C} = \mathbf{A} \times \mathbf{B}$ does *not* behave like a vector under this transformation. An object which behaves like a vector only under proper rotations is called a pseudovector. Note that as the position and momentum are true vectors, the angular momentum is a pseudo vector.

3.* Let $\phi = e^x \cos y$. Find

- The direction in which ϕ is increasing most rapidly at $(1, -\pi/4)$ and the magnitude of the rate of increase.
- The rate of change of ϕ with distance at $(0, \pi/3)$ in the direction $\hat{\mathbf{i}} + \hat{\mathbf{j}}\sqrt{3}$.
- The direction and magnitude of $\nabla\phi$ at $(0, \pi)$.

4 Calculate the gradient of $(x^2 + y^2 + z^2)^{-1/2}$ in Cartesian coordinates and of r^{-1} in spherical coordinates.

5* Given

$$\mathbf{v} = e^{kx} \sin(ky) \hat{\mathbf{i}} + e^{kx} \cos(ky) \hat{\mathbf{j}},$$

verify that $\nabla \cdot \mathbf{v} = 0$ and $\nabla \times \mathbf{v} = 0$. Note, however, that \mathbf{v} does not vanish at minus infinity.

6. Calculate $\nabla\Phi$ where $\Phi(\mathbf{r}) = \mathbf{p} \cdot \mathbf{r}/r^3$. Sketch $\nabla\Phi$ for $\mathbf{p} = p\hat{\mathbf{k}}$

7*. Consider the function $F(\mathbf{r}) = \hat{\mathbf{i}} \times \mathbf{r}$.

(a) Calculate directly the line integral of $F(\mathbf{r})$ around a circle in the yz plane centered at 0 with radius a .

(b) Calculate the line integral by using Stoke's theorem.

8*. Griffiths 1.39

9.* Use the totally antisymmetric tensors ϵ_{ijk} etc. to prove vector identity (8) in the flyleaf of Griffiths.